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The paper's lead author, Allan Zhao, told MIT News said that despite the variety of tasks robots are used for, their designs tend to be "all very similar in their shape or design."

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MIT builds a system to help robots design themselves ...

robots for minimally invasive surgery and microsurgery. In this paper, we look back through the last 25 years at how surgical robotics has evolved from a niche research field to a major area of innovation and development. With improved safety, efficacy and reduced

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costs, robotic platforms will soon approach a tipping point, moving

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In this paper, we present an end-to-end system for addressing tasks with modular robots, and demonstrate that it is capable of accomplishing challenging

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multi-part tasks in hardware experiments. The system consists of four tightly integrated components: (1) ...

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10:00-11:30 Regular session MoAT9
Room T9 Award Session 9: Finalists for

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Best Application Paper: 11:45-13:15
Regular session MoBT9 Room T9
Autonomous Vehicles: Behavior:
14:00-15:30 Regular session MoCT9
Room T9 Automation at Micro-Nano
Scales: 16:30-18:00 Regular session
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5 Coolest ROBOTS You Can Actually

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The robots that Schuerle used in this study are 35 hundredths of a millimeter long, similar in size to a single cell, and can be controlled by applying an external magnetic field. This bioinspired robot, which the researchers call an “artificial bacterial flagellum,” consists of a tiny helix that resembles the flagella

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that many bacteria use to propel themselves.

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We have 25 awesome Robot Crafts and Activities that they will love! On the next rainy day - or really hot day - pull these out and let your kids get creative with all

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these fun robots! The best part, most of them can be [...] Article by Chrissy {The Taylor House} 1.9k.

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Robot Finger Template Look at the drawing of the bones in your hand (below)...

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Multi-Robot Task Allocation is a crucial issue before performing a certain task. This paper deals with a distributed task allocation method based on some special relation defined according to the performance of history cooperation

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between two robots. The algorithm we propose here is named TARARC—a Task Allocation algorithm based on Robot Ability and Relevance with group Collaboration, where ...

[PDF] A Multi-Robots Task Allocation Algorithm Based on ...
robots—that are capable of replacing

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human labor in a range of tasks. Industrial robots are argued to have already deeply impacted the labor market and are expected to transform it in the decades to come (e.g., Brynjolfsson and McAfee, 2012; Ford, 2016). Indeed, between 1993 and 2007 the stock of robots in the United States and Western

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ROBOTS AND JOBS: NATIONAL BUREAU OF ECONOMIC RESEARCH

In a preprint paper, Google and University of California, Berkeley researchers propose a framework for helping robots navigate around obstacles and humans.

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Google's AI helps robots navigate around humans in offices ...

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TuCT4.1 ...

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Conference on Intelligent ...

the robot trajectory and the map building are performed once the measurements have been collected. Set-membership methods have often been considered for the localization of robots (see, e.g., [11] and [22] if the problem is linear, and also [1] when the robot is underwater). In situations where strong

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nonlinearities are involved, interval
analysis

88 IEEE TRANSACTIONS ON ROBOTICS, VOL. 25, NO. 1, FEBRUARY ...

Using a model in which robots compete against human labor in the production of different tasks, we show that robots may

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reduce employment and wages, and that the local labor market effects of robots can be estimated by regressing the change in employment and wages on the exposure to robots in each local labor market—defined from the national penetration of robots into each industry and the ...

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